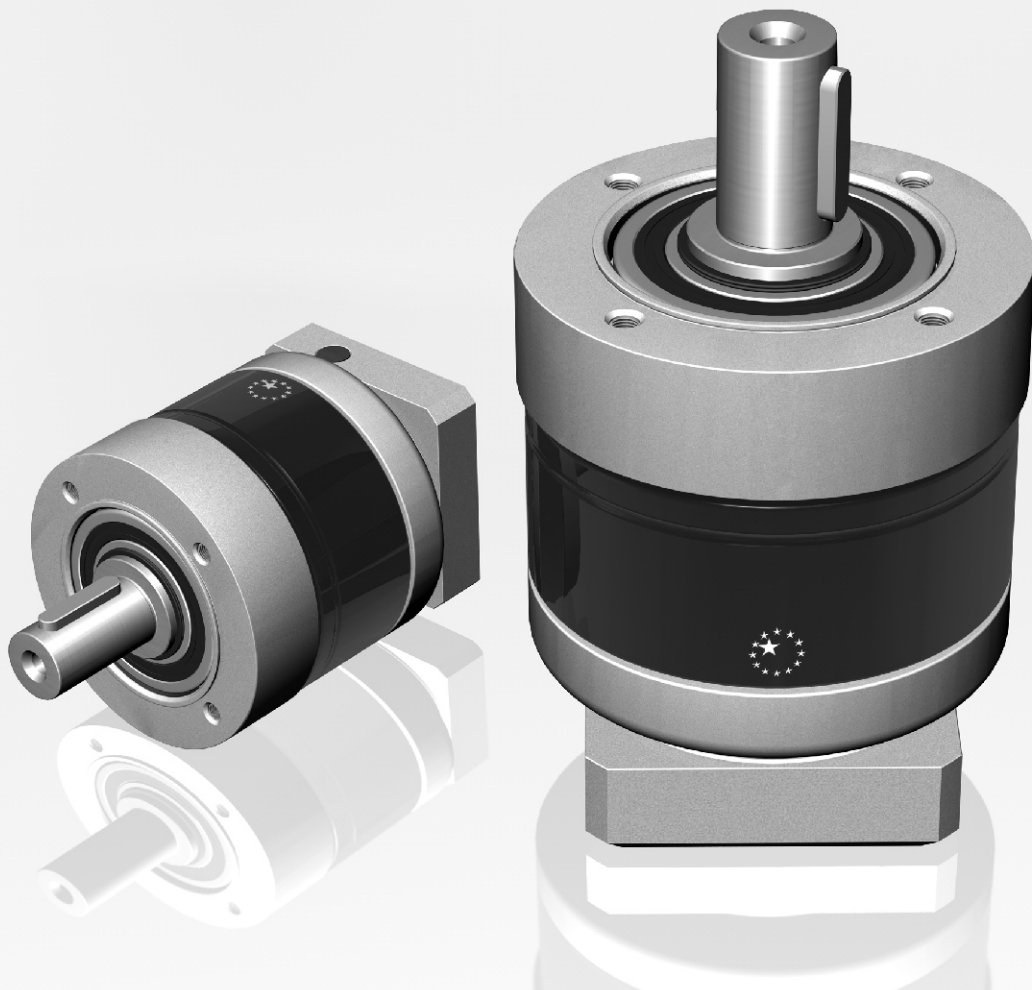


APEX DYNAMICS, INC.

PGII - SERIES
PLANETARY GEARBOX
NEW GENERATION



PGII Series

► Features:

Economic

High efficiency

Low noise

Reduced backlash

Optimized Inertia moment

Limited temperature rise

Long service life

Flexible mounting diameters

Minimized size and weight

Your motor's perfect match!!

The brand new APEX PII series. The PII series is an economic high precision planetary gearbox with excellent performance and quality. Our innovative PII series design features minimal size, light weight and high efficiency.

► Ordering Code

PGII 090

—

010

— ⁽²⁾

/

MOTOR

Motor Designation:
Manufacture Type And Model

Ratio⁽¹⁾:

1 stage: 3, 4, 5, 7, 10

2 stage: 15, 16, 20, 25, 30, 35, 40, 50, 70, 100

Gear Size:

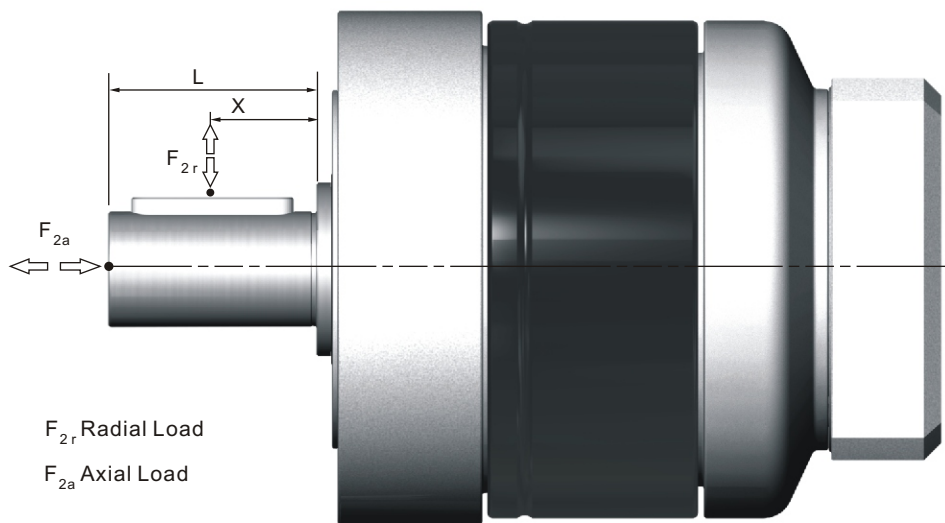
PGII : PGII A, PGII B, PGII C, PGII D, PGII E

Ordering Example : PGII 090-010 / SIEMENS 1FT6 041-4AF71
PGII 090-010-S1 / SIEMENS 1FT6 041-4AF71

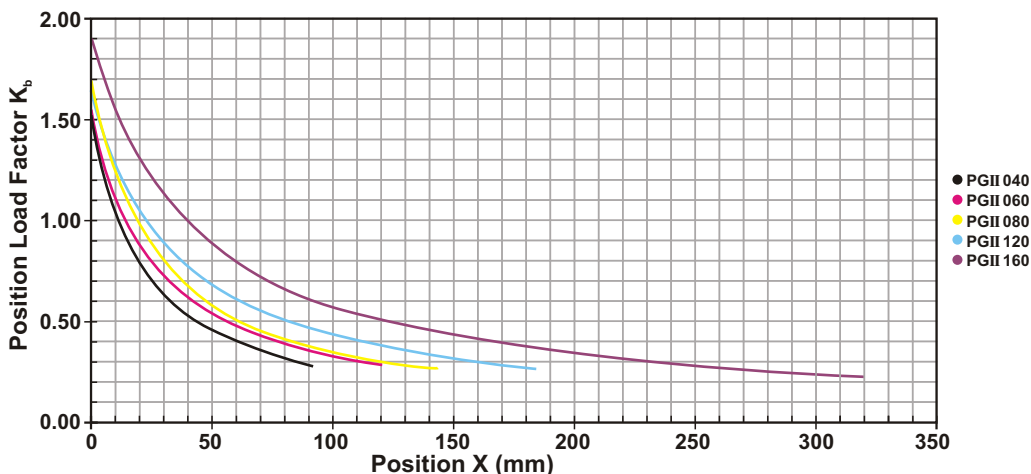
(1) Other ratios are available, please contact APEX.

(2) For PSII, PEII and PGII series, the output shaft with key (S2) is standard.
For PAII series, the S1 and S2 are both available.

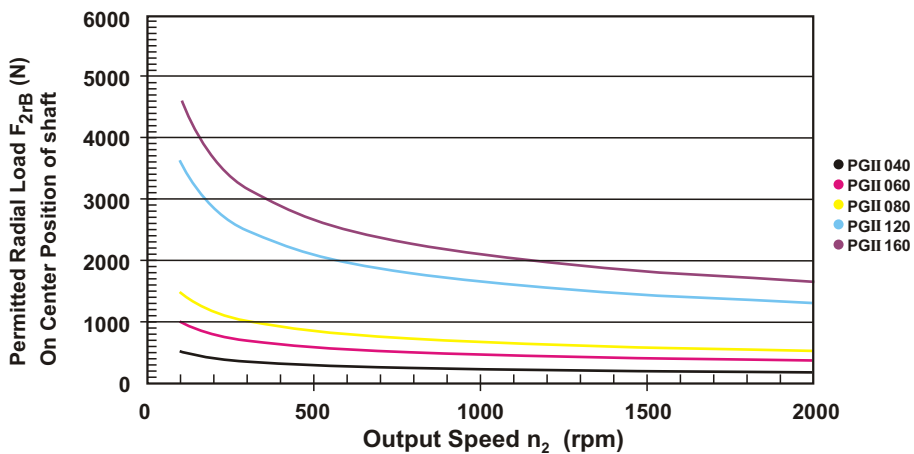
Permitted Radial And Axial Loads On Output Shaft



The permitted radial and axial loads on output shaft of the gearbox depend on the design of the gearbox supporting bearings.



If radial force F_r is not exerted on the center of the output shaft $X < 1/2xL$ or $X > 1/2xL$, the permitted radial and axial loads can be calculated by the position load factor K_b on the above diagram.



Permitted radial load F_r on center of output shaft $X = 1/2 \times L$ for various output speeds. Values provided are for 20,000 hours^(*) life.

(*) For Continuous Operation(S1), the service life reduced to 50%.

PGII Series Specifications

| PGII 040 | | 1-stage | | | | | 2-stage | | | | | | | | | |
|---|--------------------|--|------|------|------|------|--|------|------|------|------|------|------|------|------|------|
| | | Ratio ^{(1) (2)} | | | | | Ratio ^{(1) (2)} | | | | | | | | | |
| | | 3 | 4 | 5 | 7 | 10 | 15 | 16 | 20 | 25 | 30 | 35 | 40 | 50 | 70 | 100 |
| Nominal Output Torque T_{2N} | Nm | 6.3 | 8 | 8.5 | 9.8 | 8 | 6 | 7.6 | 7.6 | 8 | 5.7 | 9.1 | 7.6 | 8 | 9.1 | 8 |
| Emergency Stop Torque T_{2NOT} | Nm | 3 times T_{2N} | | | | | | | | | | | | | | |
| Max. Acceleration Torque T_{2B} | Nm | 11.3 | 14.4 | 15.3 | 17.6 | 14.4 | 10.8 | 13.7 | 13.7 | 14.4 | 10.3 | 16.4 | 13.7 | 14.4 | 16.4 | 14.4 |
| No Load Running Torque ⁽⁶⁾ | Nm | 0.05 | | | | | 0.05 | | | | | | | | | |
| Backlash ⁽³⁾ | arcmin | ≤ 8 | | | | | ≤ 10 | | | | | | | | | |
| Torsional Rigidity | Nm/arcmin | 0.5 | | | | | 0.5 | | | | | | | | | |
| Nominal Input Speed n_{1N} | rpm | 4,500 | | | | | | | | | | | | | | |
| Max. Input Speed n_{1B} | rpm | 8,000 | | | | | | | | | | | | | | |
| Max. Radial Load F_{2rB} ⁽⁴⁾ | N | 520 | | | | | | | | | | | | | | |
| Max. Axial Load F_{2aB} ⁽⁴⁾ | N | 260 | | | | | | | | | | | | | | |
| Service Life ⁽⁷⁾ | hr | 20,000 | | | | | | | | | | | | | | |
| Operating Temperature | °C | 0° C~ +90° C | | | | | | | | | | | | | | |
| Lubrication | | Synthetic lubrication grease | | | | | | | | | | | | | | |
| Degree of Protection | | IP65 | | | | | | | | | | | | | | |
| Mounting Position | | All directions | | | | | | | | | | | | | | |
| Running Noise ^{(6) (8)} | dB(A) | ≤ 60 | | | | | | | | | | | | | | |
| Efficiency η | % | $\geq 97\%$ | | | | | $\geq 94\%$ | | | | | | | | | |
| Weight | kg | $\varnothing^{(5)} \leq 8, 11, 14 = 0.7$ | | | | | $\varnothing^{(5)} \leq 8, 11, 14 = 0.8$ | | | | | | | | | |
| Moment of Inertia J_1 | kg.cm ² | $\varnothing^{(5)} \leq 8$ | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 |
| | | $\varnothing^{(5)} \leq 11$ | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 |
| | | $\varnothing^{(5)} \leq 14$ | 0.2 | 0.2 | 0.19 | 0.19 | 0.19 | 0.19 | 0.2 | 0.19 | 0.19 | 0.19 | 0.19 | 0.19 | 0.19 | 0.19 |

(1) Ratio ($i = N_{in} / N_{out}$).

(2) Other ratios are available, please contact APEX.

(3) Backlash is measured at 2% of Nominal Output Torque T_{2N} .

(4) Applied to the output shaft center at 100 rpm.

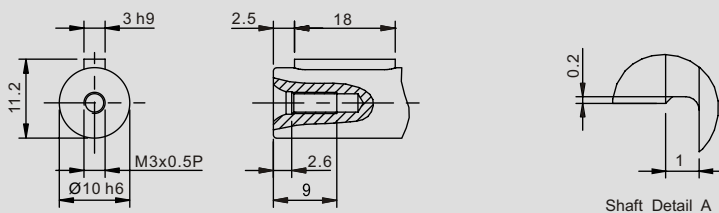
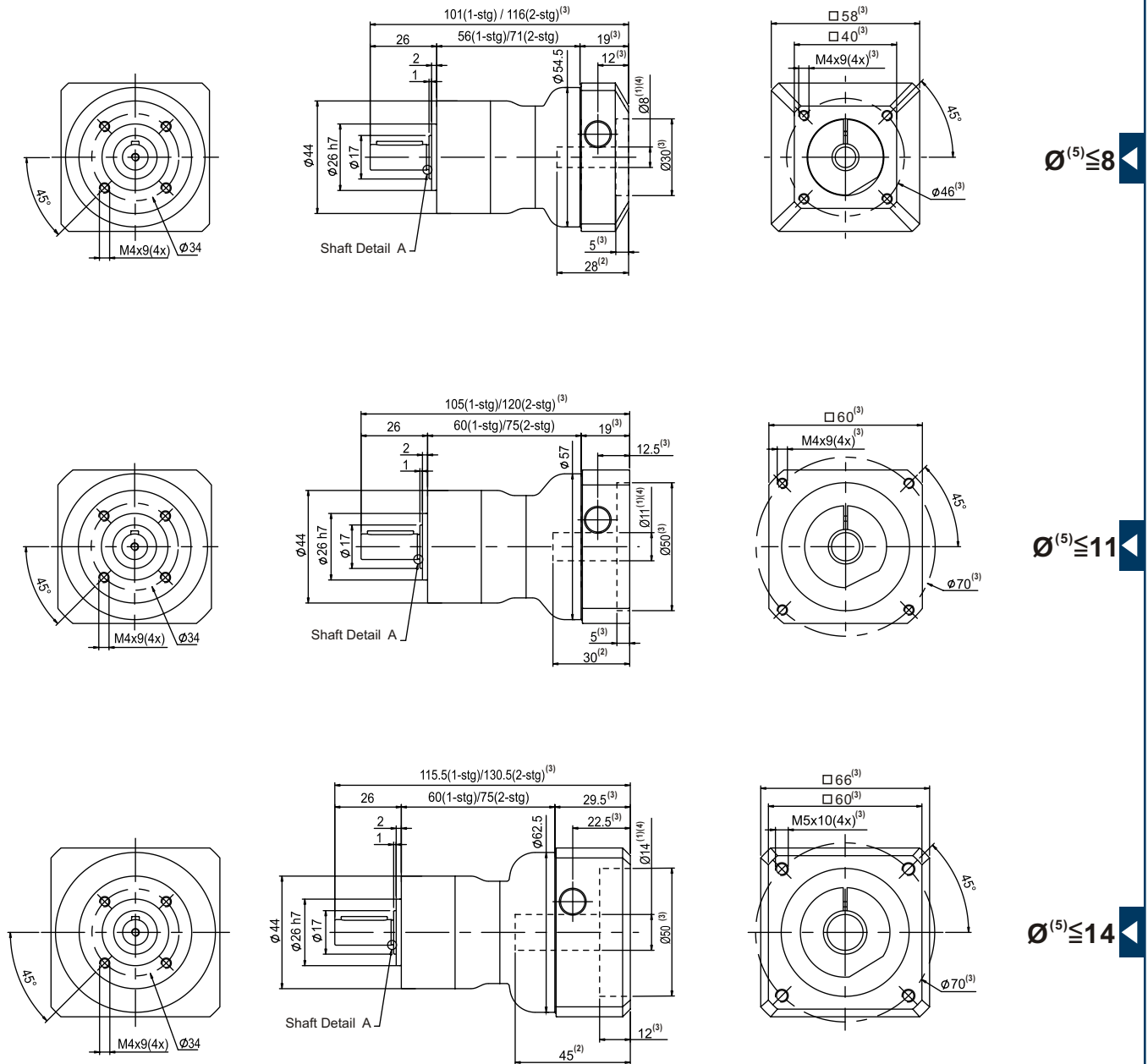
(5) \varnothing = Input shaft diameter.

(6) These values are measured at 3000 rpm without load.

(7) For continuous operation, the service life is 10000 hrs.

(8) These values are measured with ratio=10 (1-stage) and ratio=100 (2-stage) at 3000 rpm.

PGII Series Dimension



Shaft Detail

- (1) This dimension refers to motor shaft diameter.
- (2) The maximum motor shaft length. For other Motor specific dimensions, please contact APEX.
- (3) Input dimensions vary according to motor flange.
- (4) Please contact APEX, if there is no proper dimension.
- (5) Ø= Input shaft diameter.

PGII Series Specifications

| PGII 060 | | 1-stage | | | | | 2-stage | | | | | | | | | | |
|---|--------------------|---|------|------|------|------|---|------|------|------|------|------|------|------|------|------|------|
| | | Ratio ^{(1) (2)} | | | | | Ratio ^{(1) (2)} | | | | | | | | | | |
| | | 3 | 4 | 5 | 7 | 10 | 15 | 16 | 20 | 25 | 30 | 35 | 40 | 50 | 70 | 100 | |
| Nominal Output Torque T_{2N} | Nm | 21.3 | 27.6 | 28.5 | 33.6 | 27 | 20.1 | 26.4 | 26 | 27 | 19.5 | 31.5 | 25.6 | 26.5 | 30.8 | 27 | |
| Emergency Stop Torque T_{2NOT} | Nm | 3 times T_{2N} | | | | | | | | | | | | | | | |
| Max. Acceleration Torque T_{2B} | Nm | 38.3 | 49.7 | 51.3 | 60.5 | 48.6 | 36.2 | 47.5 | 46.8 | 48.6 | 35.1 | 56.7 | 46.1 | 47.7 | 55.4 | 48.6 | |
| No Load Running Torque ⁽⁸⁾ | Nm | 0.1 | | | | | 0.1 | | | | | | | | | | |
| Backlash ⁽³⁾ | arcmin | ≤ 7 | | | | | ≤ 9 | | | | | | | | | | |
| Torsional Rigidity | Nm/arcmin | 2 | | | | | 2 | | | | | | | | | | |
| Nominal Input Speed n_{1N} | rpm | 4,000 | | | | | | | | | | | | | | | |
| Max. Input Speed n_{1B} | rpm | 6,000 | | | | | | | | | | | | | | | |
| Max. Radial Load F_{2rB} ⁽⁴⁾ | N | 1,030 | | | | | | | | | | | | | | | |
| Max. Axial Load F_{2aB} ⁽⁴⁾ | N | 515 | | | | | | | | | | | | | | | |
| Service Life ⁽⁷⁾ | hr | 20,000 | | | | | | | | | | | | | | | |
| Operating Temperature | °C | 0° C~ +90° C | | | | | | | | | | | | | | | |
| Lubrication | | Synthetic lubrication grease | | | | | | | | | | | | | | | |
| Degree of Protection | | IP65 | | | | | | | | | | | | | | | |
| Mounting Position | | All directions | | | | | | | | | | | | | | | |
| Running Noise ^{(6) (8)} | dB(A) | ≤ 62 | | | | | | | | | | | | | | | |
| Efficiency η | % | $\geq 97\%$ | | | | | $\geq 94\%$ | | | | | | | | | | |
| Weight | kg | $\varnothing^{(5)} \leq 8, 11, 14 = 1.2$ $\varnothing^{(5)} \leq 19 = 1.9$ | | | | | $\varnothing^{(5)} \leq 8, 11, 14 = 1.5$ $\varnothing^{(5)} \leq 19 = 2.2$ | | | | | | | | | | |
| Moment of Inertia J_1 | kg.cm ² | $\varnothing^{(5)} \leq 8$ | 0.12 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 |
| | | $\varnothing^{(5)} \leq 11$ | 0.19 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 | 0.16 |
| | | $\varnothing^{(5)} \leq 14$ | 0.22 | 0.2 | 0.2 | 0.2 | 0.2 | 0.2 | 0.2 | 0.2 | 0.2 | 0.2 | 0.2 | 0.2 | 0.2 | 0.2 | 0.2 |
| | | $\varnothing^{(5)} \leq 19$ | 1.53 | 1.51 | 1.51 | 1.51 | 1.51 | 1.51 | 1.51 | 1.51 | 1.51 | 1.51 | 1.51 | 1.51 | 1.51 | 1.51 | 1.51 |

(1) Ratio ($i = N_{in} / N_{out}$).

(2) Other ratios are available, please contact APEX.

(3) Backlash is measured at 2% of Nominal Output Torque T_{2N} .

(4) Applied to the output shaft center at 100 rpm.

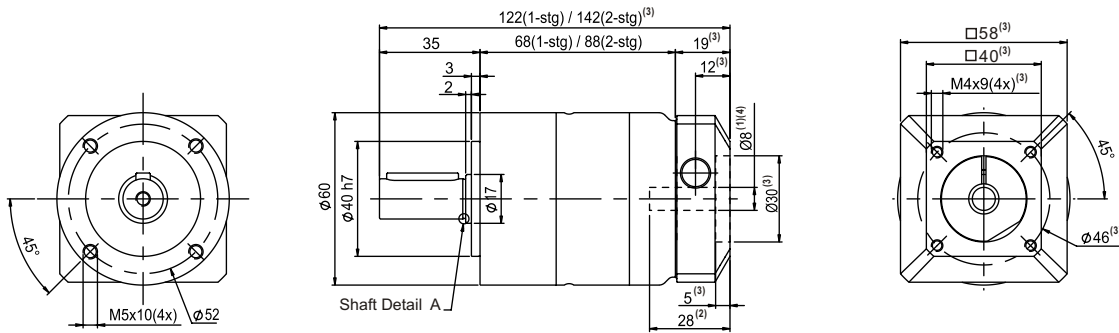
(5) \varnothing = Input shaft diameter.

(6) These values are measured at 3000 rpm without load.

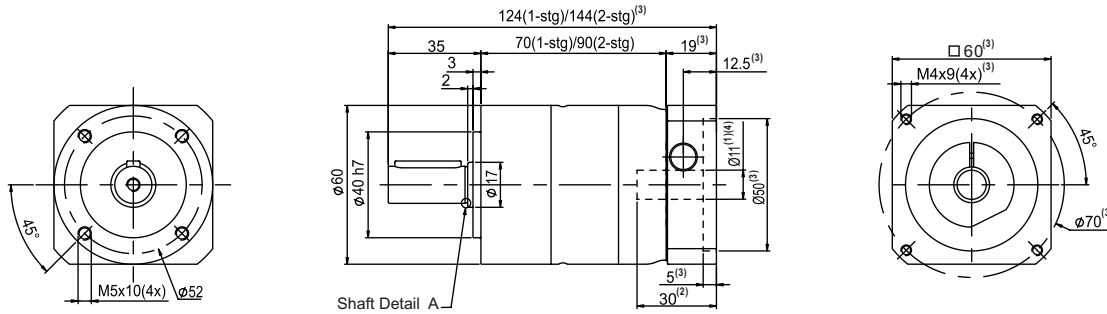
(7) For continuous operation, the service life is 10000 hrs.

(8) These values are measured with ratio=10 (1-stage) and ratio=100 (2-stage) at 3000 rpm.

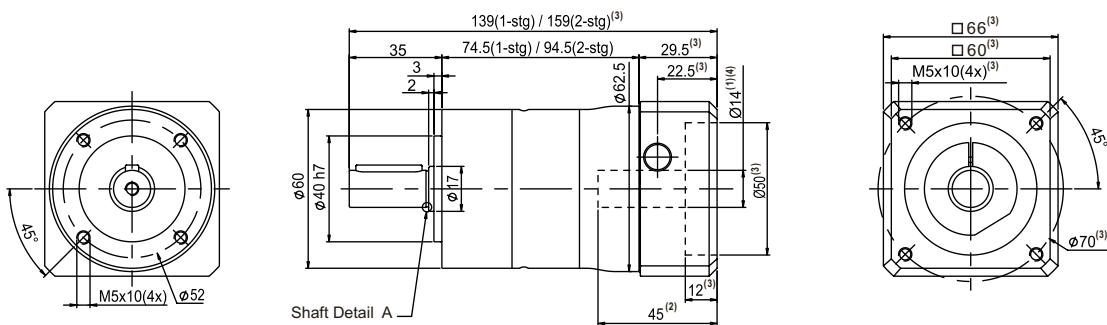
PGII Series Dimension



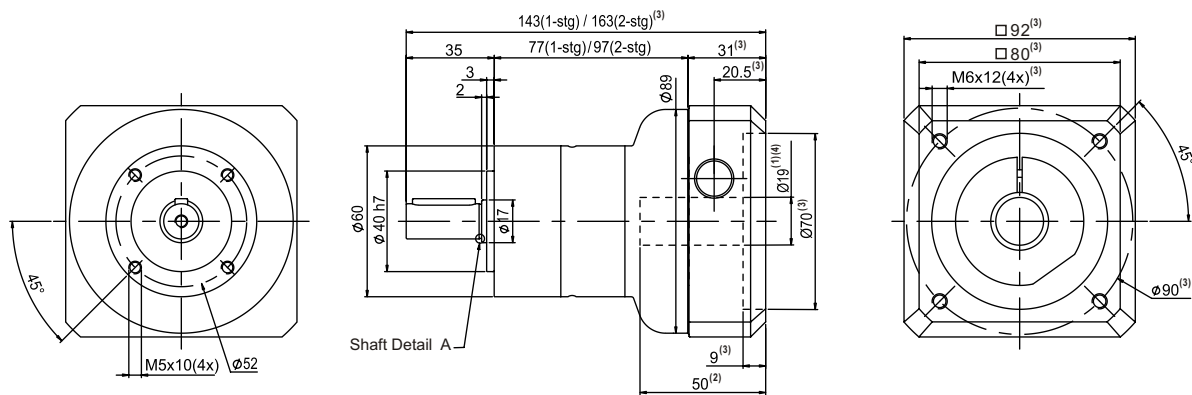
Ø⁽⁵⁾ ≤ 8



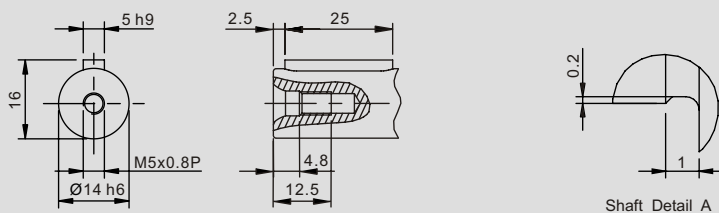
Ø⁽⁵⁾ ≤ 11



Ø⁽⁵⁾ ≤ 14



Ø⁽⁵⁾ ≤ 19



Shaft Detail

- (1) This dimension refers to motor shaft diameter.
- (2) The maximum motor shaft length. For other Motor specific dimensions, please contact APEX.
- (3) Input dimensions vary according to motor flange.
- (4) Please contact APEX, if there is no proper dimension.
- (5) Ø= Input shaft diameter.

PGII Series Specifications

| PGII 080 | | 1-stage | | | | | 2-stage | | | | | | | | | | |
|---|--------------------|--|------|------|------|------|--|------|------|------|------|------|------|------|------|------|------|
| | | Ratio ^{(1) (2)} | | | | | Ratio ^{(1) (2)} | | | | | | | | | | |
| | | 3 | 4 | 5 | 7 | 10 | 15 | 16 | 20 | 25 | 30 | 35 | 40 | 50 | 70 | 100 | |
| Nominal Output Torque T_{2N} | Nm | 47 | 60 | 62 | 73 | 59 | 45 | 58 | 57 | 59 | 43 | 69 | 56 | 58 | 68 | 61 | |
| Emergency Stop Torque T_{2NOT} | Nm | 3 times T_{2N} | | | | | | | | | | | | | | | |
| Max. Acceleration Torque T_{2B} | Nm | 85 | 108 | 112 | 131 | 106 | 81 | 104 | 103 | 106 | 77 | 124 | 101 | 104 | 122 | 110 | |
| No Load Running Torque ⁽⁸⁾ | Nm | 0.4 | | | | | 0.3 | | | | | | | | | | |
| Backlash ⁽³⁾ | arcmin | ≤ 6 | | | | | ≤ 8 | | | | | | | | | | |
| Torsional Rigidity | Nm/arcmin | 8 | | | | | 8 | | | | | | | | | | |
| Nominal Input Speed n_{1N} | rpm | 3,600 | | | | | | | | | | | | | | | |
| Max. Input Speed n_{1B} | rpm | 6,000 | | | | | | | | | | | | | | | |
| Max. Radial Load F_{2rB} ⁽⁴⁾ | N | 1,570 | | | | | | | | | | | | | | | |
| Max. Axial Load F_{2aB} ⁽⁴⁾ | N | 785 | | | | | | | | | | | | | | | |
| Service Life ⁽⁷⁾ | hr | 20,000 | | | | | | | | | | | | | | | |
| Operating Temperature | °C | 0° C~ +90° C | | | | | | | | | | | | | | | |
| Lubrication | | Synthetic lubrication grease | | | | | | | | | | | | | | | |
| Degree of Protection | | IP65 | | | | | | | | | | | | | | | |
| Mounting Position | | All directions | | | | | | | | | | | | | | | |
| Running Noise ^{(6) (8)} | dB(A) | ≤ 64 | | | | | | | | | | | | | | | |
| Efficiency η | % | $\geq 97\%$ | | | | | $\geq 94\%$ | | | | | | | | | | |
| Weight | kg | $\varnothing^{(5)} \leq 14 = 2.4$ $\varnothing^{(5)} \leq 19, 24, 28 = 3.4$ | | | | | $\varnothing^{(5)} \leq 14, 19 = 3.9$ $\varnothing^{(5)} \leq 24, 28 = 4.3$ | | | | | | | | | | |
| Moment of Inertia J_1 | kg.cm ² | $\varnothing^{(5)} \leq 14$ | 0.36 | 0.24 | 0.22 | 0.21 | 0.2 | 0.22 | 0.24 | 0.22 | 0.22 | 0.2 | 0.22 | 0.2 | 0.2 | 0.2 | 0.2 |
| | | $\varnothing^{(5)} \leq 19$ | 1.7 | 1.58 | 1.56 | 1.55 | 1.54 | 1.56 | 1.58 | 1.56 | 1.56 | 1.54 | 1.56 | 1.54 | 1.54 | 1.54 | 1.54 |
| | | $\varnothing^{(5)} \leq 24$ | 2.24 | 2.12 | 2.1 | 2.09 | 2.09 | 2.1 | 2.12 | 2.1 | 2.1 | 2.09 | 2.1 | 2.09 | 2.09 | 2.09 | 2.09 |
| | | $\varnothing^{(5)} \leq 28$ | 2.68 | 2.55 | 2.53 | 2.52 | 2.52 | 2.53 | 2.55 | 2.53 | 2.53 | 2.52 | 2.53 | 2.52 | 2.52 | 2.52 | 2.52 |

(1) Ratio ($i = N_{in} / N_{out}$).

(2) Other ratios are available, please contact APEX.

(3) Backlash is measured at 2% of Nominal Output Torque T_{2N} .

(4) Applied to the output shaft center at 100 rpm.

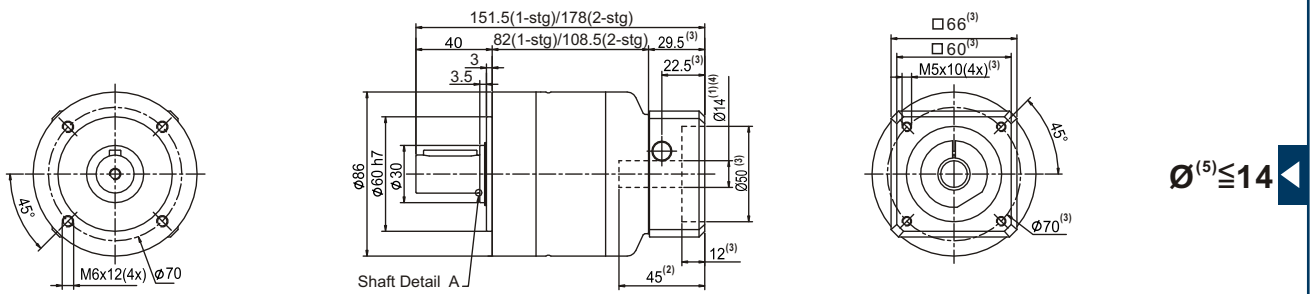
(5) \varnothing = Input shaft diameter.

(6) These values are measured at 3000 rpm without load.

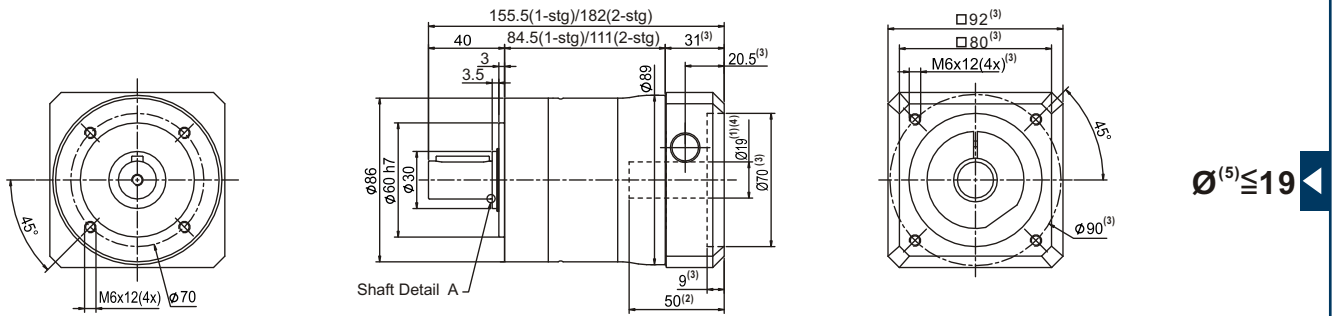
(7) For continuous operation, the service life is 10000 hrs.

(8) These values are measured with ratio=10 (1-stage) and ratio=100 (2-stage) at 3000 rpm.

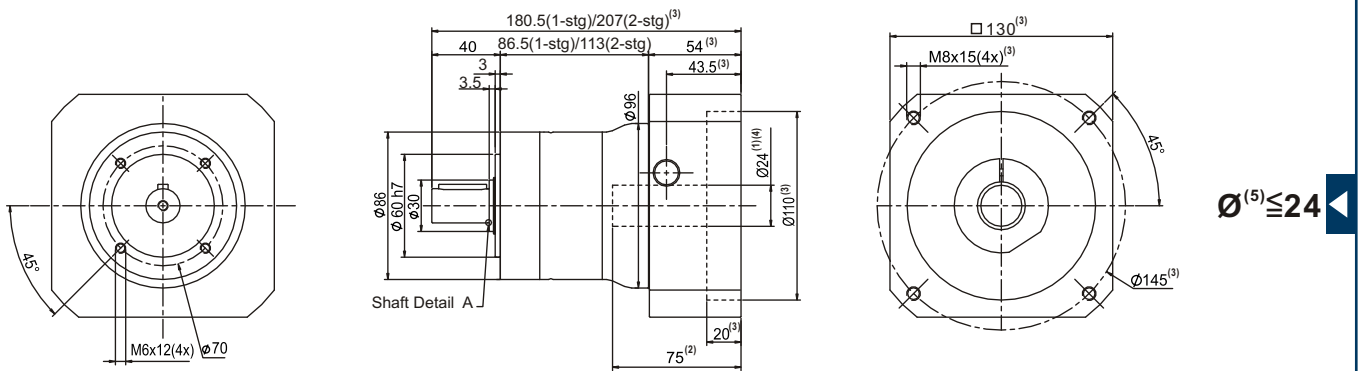
PGII Series Dimension



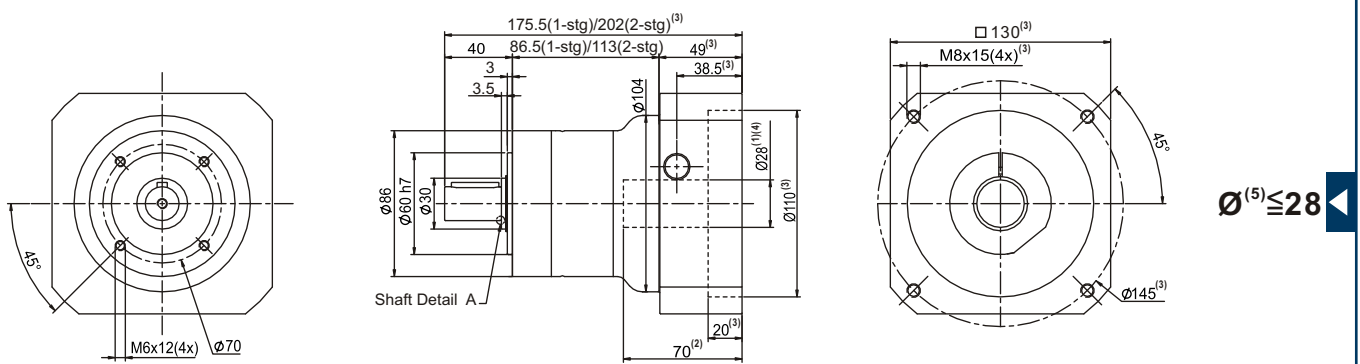
Ø⁽⁵⁾ ≤ 14



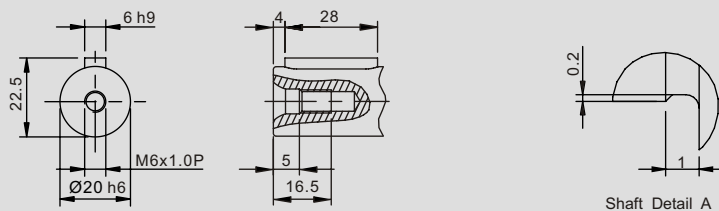
Ø⁽⁵⁾ ≤ 19



Ø⁽⁵⁾ ≤ 24



Ø⁽⁵⁾ ≤ 28



Shaft Detail

- (1) This dimension refers to motor shaft diameter.
- (2) The maximum motor shaft length. For other Motor specific dimensions, please contact APEX.
- (3) Input dimensions vary according to motor flange.
- (4) Please contact APEX, if there is no proper dimension.
- (5) Ø= Input shaft diameter.

PGII Series Specifications

| PGII 120 | | 1-stage | | | | | 2-stage | | | | | | | | | | |
|---|--------------------|--|------|------|------|------|--|------|------|------|------|------|------|------|------|------|------|
| | | Ratio ^{(1) (2)} | | | | | Ratio ^{(1) (2)} | | | | | | | | | | |
| | | 3 | 4 | 5 | 7 | 10 | 15 | 16 | 20 | 25 | 30 | 35 | 40 | 50 | 70 | 100 | |
| Nominal Output Torque T_{2N} | Nm | 74 | 95 | 98 | 116 | 94 | 72 | 93 | 92 | 94 | 70 | 110 | 90 | 92 | 108 | 97 | |
| Emergency Stop Torque T_{2NOT} | Nm | 3 times T_{2N} | | | | | | | | | | | | | | | |
| Max. Acceleration Torque T_{2B} | Nm | 133 | 171 | 176 | 209 | 169 | 130 | 167 | 166 | 169 | 126 | 198 | 162 | 166 | 194 | 175 | |
| No Load Running Torque ⁽⁶⁾ | Nm | 0.8 | | | | | 0.4 | | | | | | | | | | |
| Backlash ⁽³⁾ | arcmin | ≤ 6 | | | | | ≤ 8 | | | | | | | | | | |
| Torsional Rigidity | Nm/arcmin | 12 | | | | | 12 | | | | | | | | | | |
| Nominal Input Speed n_{1N} | rpm | 3,600 | | | | | | | | | | | | | | | |
| Max. Input Speed n_{1B} | rpm | 4,800 | | | | | | | | | | | | | | | |
| Max. Radial Load F_{2RB} ⁽⁴⁾ | N | 3,590 | | | | | | | | | | | | | | | |
| Max. Axial Load F_{2aB} ⁽⁴⁾ | N | 1,795 | | | | | | | | | | | | | | | |
| Service Life ⁽⁷⁾ | hr | 20,000 | | | | | | | | | | | | | | | |
| Operating Temperature | °C | 0° C~ +90° C | | | | | | | | | | | | | | | |
| Lubrication | | Synthetic lubrication grease | | | | | | | | | | | | | | | |
| Degree of Protection | | IP65 ⁽⁸⁾ | | | | | | | | | | | | | | | |
| Mounting Position | | All directions | | | | | | | | | | | | | | | |
| Running Noise ^{(6) (8)} | dB(A) | ≤ 66 | | | | | | | | | | | | | | | |
| Efficiency η | % | $\geq 97\%$ | | | | | $\geq 94\%$ | | | | | | | | | | |
| Weight | kg | $\varnothing^{(5)} \leq 19, 24, 28 = 6.2$ $\varnothing^{(5)} \leq 32, 35 = 7.8$ $\varnothing^{(5)} \leq 38 = 11.7$ | | | | | $\varnothing^{(5)} \leq 19, 24, 28 = 8.3$ $\varnothing^{(5)} \leq 32, 35 = 9.9$ $\varnothing^{(5)} \leq 38 = 13.8$ | | | | | | | | | | |
| Moment of Inertia J_1 | kg.cm ² | $\varnothing^{(5)} \leq 19$ | 2.2 | 1.73 | 1.65 | 1.61 | 1.6 | 1.65 | 1.73 | 1.65 | 1.65 | 1.6 | 1.65 | 1.6 | 1.6 | 1.6 | 1.6 |
| | | $\varnothing^{(5)} \leq 24$ | 2.74 | 2.27 | 2.19 | 2.15 | 2.14 | 2.19 | 2.27 | 2.19 | 2.19 | 2.14 | 2.19 | 2.14 | 2.14 | 2.14 | 2.14 |
| | | $\varnothing^{(5)} \leq 28$ | 3.17 | 2.7 | 2.62 | 2.58 | 2.57 | 2.62 | 2.7 | 2.62 | 2.62 | 2.57 | 2.62 | 2.57 | 2.57 | 2.57 | 2.57 |
| | | $\varnothing^{(5)} \leq 32$ | 7.77 | 7.3 | 7.22 | 7.18 | 7.17 | 7.22 | 7.3 | 7.22 | 7.22 | 7.17 | 7.22 | 7.17 | 7.17 | 7.17 | 7.17 |
| | | $\varnothing^{(5)} \leq 35$ | 10.8 | 10.3 | 10.2 | 10.2 | 10.2 | 10.2 | 10.3 | 10.2 | 10.2 | 10.2 | 10.2 | 10.2 | 10.2 | 10.2 | 10.2 |
| | | $\varnothing^{(5)} \leq 38$ | 14 | 13.5 | 13.4 | 13.4 | 13.4 | 13.4 | 13.5 | 13.4 | 13.4 | 13.4 | 13.4 | 13.4 | 13.4 | 13.4 | 13.4 |

(1) Ratio ($i = N_{in} / N_{out}$).

(2) Other ratios are available, please contact APEX.

(3) Backlash is measured at 2% of Nominal Output Torque T_{2N} .

(4) Applied to the output shaft center at 100 rpm.

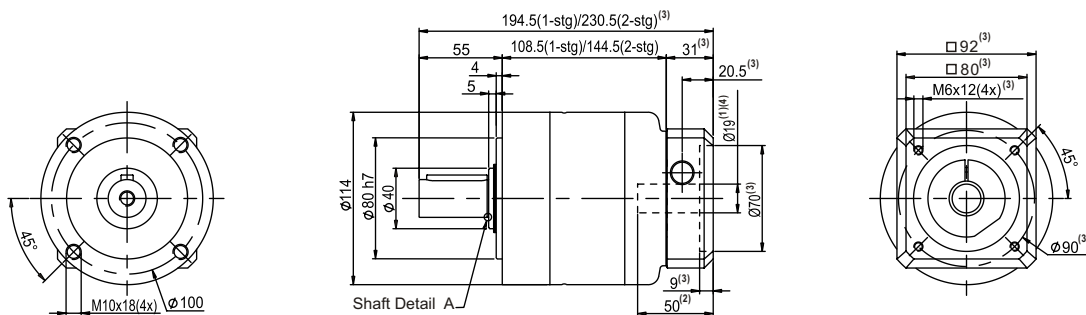
(5) \varnothing = Input shaft diameter.

(6) These values are measured at 3000 rpm without load.

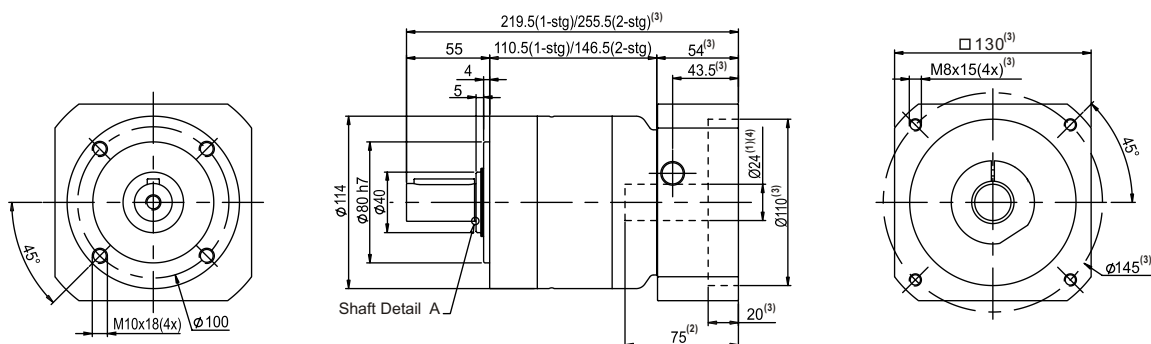
(7) For continuous operation, the service life is 10000 hrs.

(8) These values are measured with ratio=10 (1-stage) and ratio=100 (2-stage) at 3000 rpm.

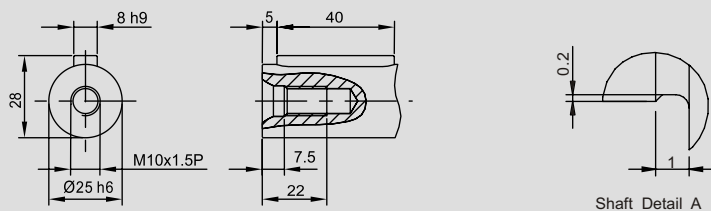
PGII Series Dimension



Ø⁽⁵⁾ ≤ 19



Ø⁽⁵⁾ ≤ 24

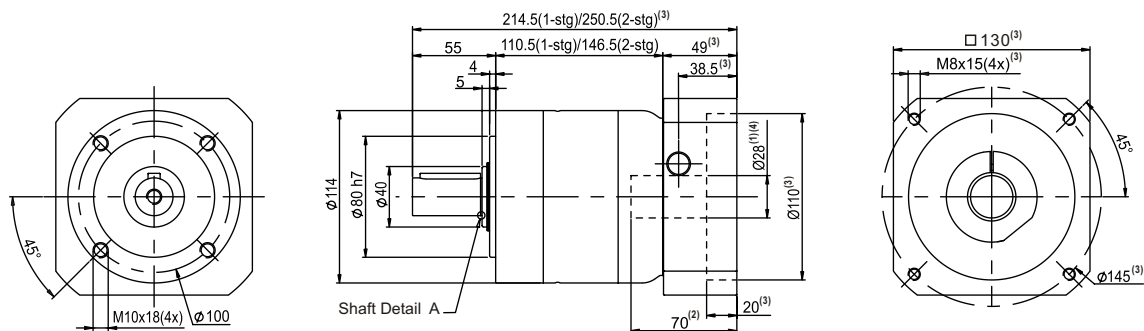


Shaft Detail

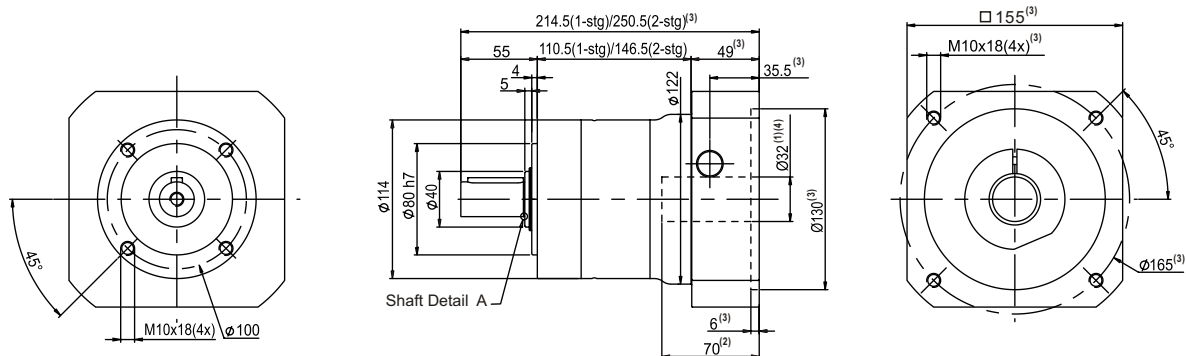
- (1) This dimension refers to motor shaft diameter.
- (2) The maximum motor shaft length. For other Motor specific dimensions, please contact APEX.
- (3) Input dimensions vary according to motor flange.
- (4) Please contact APEX, if there is no proper dimension.
- (5) Ø= Input shaft diameter.

PGII Series Dimension

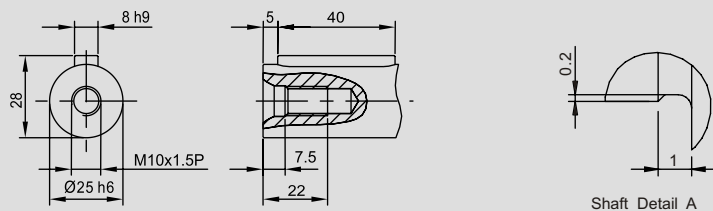
▶ $\emptyset^{(5)} \leq 28$



▶ $\emptyset^{(5)} \leq 32$

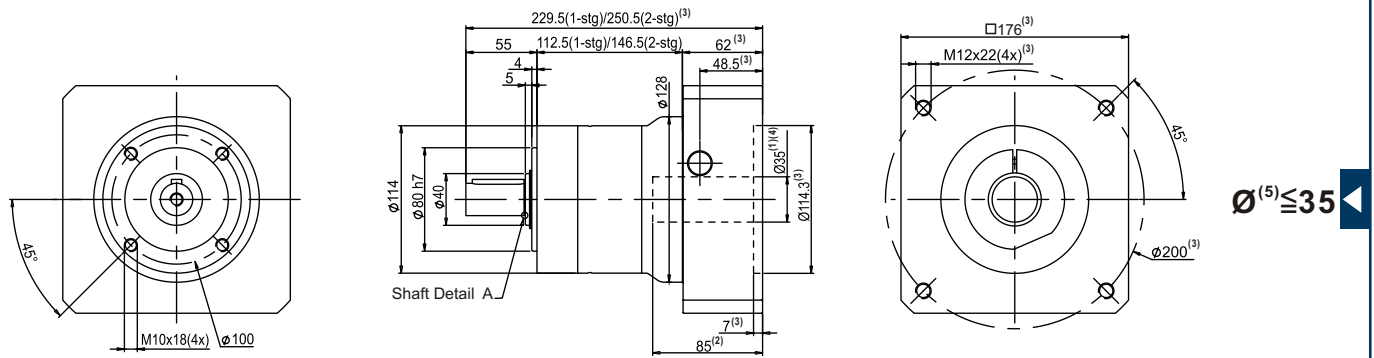


▶ Shaft Detail

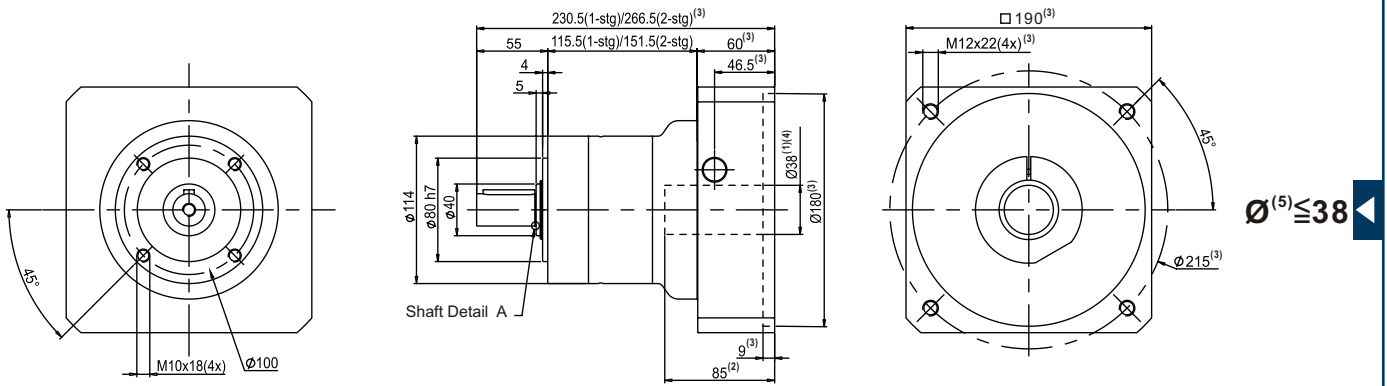


- (1) This dimension refers to motor shaft diameter.
- (2) The maximum motor shaft length. For other Motor specific dimensions, please contact APEX.
- (3) Input dimensions vary according to motor flange.
- (4) Please contact APEX, if there is no proper dimension.
- (5) \emptyset = Input shaft diameter.

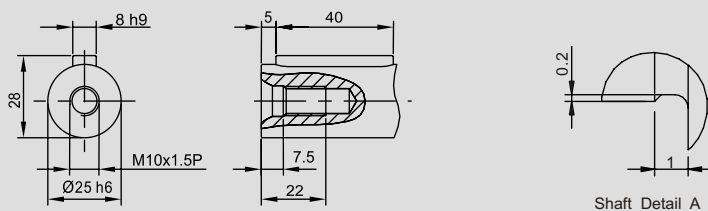
PGII Series Dimension



Ø⁽⁵⁾ ≤ 35



Ø⁽⁵⁾ ≤ 38



Shaft Detail

- (1) This dimension refers to motor shaft diameter.
- (2) The maximum motor shaft length. For other Motor specific dimensions, please contact APEX.
- (3) Input dimensions vary according to motor flange.
- (4) Please contact APEX, if there is no proper dimension.
- (5) Ø= Input shaft diameter.

PGII Series Specifications

| PGII 160 | | 1-stage | | | | | 2-stage | | | | | | | | | | |
|---|--------------------|--|------|------|------|------|--|------|------|------|------|------|------|------|------|------|------|
| | | Ratio ^{(1) (2)} | | | | | Ratio ^{(1) (2)} | | | | | | | | | | |
| | | 3 | 4 | 5 | 7 | 10 | 15 | 16 | 20 | 25 | 30 | 35 | 40 | 50 | 70 | 100 | |
| Nominal Output Torque T_{2N} | Nm | 145 | 188 | 194 | 225 | 155 | 140 | 182 | 181 | 186 | 137 | 218 | 177 | 183 | 214 | 162 | |
| Emergency Stop Torque T_{2NOT} | Nm | 3 times T_{2N} | | | | | | | | | | | | | | | |
| Max. Acceleration Torque T_{2B} | Nm | 261 | 338 | 348 | 406 | 279 | 253 | 328 | 326 | 335 | 246 | 393 | 319 | 329 | 386 | 292 | |
| No Load Running Torque ⁽⁶⁾ | Nm | 2.5 | | | | | 0.8 | | | | | | | | | | |
| Backlash ⁽³⁾ | arcmin | ≤ 6 | | | | | ≤ 8 | | | | | | | | | | |
| Torsional Rigidity | Nm/arcmin | 16 | | | | | 16 | | | | | | | | | | |
| Nominal Input Speed n_{1N} | rpm | 2,500 | | | | | | | | | | | | | | | |
| Max. Input Speed n_{1B} | rpm | 3,600 | | | | | | | | | | | | | | | |
| Max. Radial Load F_{2RB} ⁽⁴⁾ | N | 4,690 | | | | | | | | | | | | | | | |
| Max. Axial Load F_{2aB} ⁽⁴⁾ | N | 2,345 | | | | | | | | | | | | | | | |
| Service Life ⁽⁷⁾ | hr | 20,000 | | | | | | | | | | | | | | | |
| Operating Temperature | °C | 0° C~ +90° C | | | | | | | | | | | | | | | |
| Lubrication | | Synthetic lubrication grease | | | | | | | | | | | | | | | |
| Degree of Protection | | IP65 | | | | | | | | | | | | | | | |
| Mounting Position | | All directions | | | | | | | | | | | | | | | |
| Running Noise ^{(6) (8)} | dB(A) | ≤ 68 | | | | | | | | | | | | | | | |
| Efficiency η | % | $\geq 97\%$ | | | | | $\geq 94\%$ | | | | | | | | | | |
| Weight | kg | $\varnothing^{(5)} \leq 24, 28 = 11.5$ $\varnothing^{(5)} \leq 32, 35 = 13.1$ $\varnothing^{(5)} \leq 38, 42 = 17.1$ | | | | | $\varnothing^{(5)} \leq 19, 24, 28 = 15.5$ $\varnothing^{(5)} \leq 32, 35 = 17.1$ $\varnothing^{(5)} \leq 38 = 20.9$ | | | | | | | | | | |
| Moment of Inertia J_1 | kg.cm ² | $\varnothing^{(5)} \leq 19$ | - | - | - | - | - | 1.85 | 2.18 | 1.85 | 1.85 | 1.69 | 1.85 | 1.69 | 1.69 | 1.69 | 1.69 |
| | | $\varnothing^{(5)} \leq 24$ | 4.52 | 2.73 | 2.4 | 2.26 | 2.23 | 2.4 | 2.73 | 2.4 | 2.4 | 2.23 | 2.4 | 2.23 | 2.23 | 2.23 | 2.23 |
| | | $\varnothing^{(5)} \leq 28$ | 4.94 | 3.15 | 2.82 | 2.68 | 2.65 | 2.82 | 3.15 | 2.82 | 2.82 | 2.65 | 2.82 | 2.65 | 2.65 | 2.65 | 2.65 |
| | | $\varnothing^{(5)} \leq 32$ | 9.7 | 7.91 | 7.58 | 7.44 | 7.41 | 7.58 | 7.91 | 7.58 | 7.58 | 7.41 | 7.58 | 7.41 | 7.41 | 7.41 | 7.41 |
| | | $\varnothing^{(5)} \leq 35$ | 12.8 | 11 | 10.7 | 10.5 | 10.5 | 10.7 | 11 | 10.7 | 10.7 | 10.5 | 10.7 | 10.5 | 10.5 | 10.5 | 10.5 |
| | | $\varnothing^{(7)} \leq 38$ | 16 | 14.2 | 13.9 | 13.7 | 13.7 | 13.9 | 14.2 | 13.9 | 13.9 | 13.7 | 13.9 | 13.7 | 13.7 | 13.7 | 13.7 |
| | | $\varnothing^{(7)} \leq 42$ | 24.5 | 22.7 | 22.4 | 22.2 | 22.2 | - | - | - | - | - | - | - | - | - | - |

(1) Ratio ($i = N_{in} / N_{out}$).

(2) Other ratios are available, please contact APEX.

(3) Backlash is measured at 2% of Nominal Output Torque T_{2N} .

(4) Applied to the output shaft center at 100 rpm.

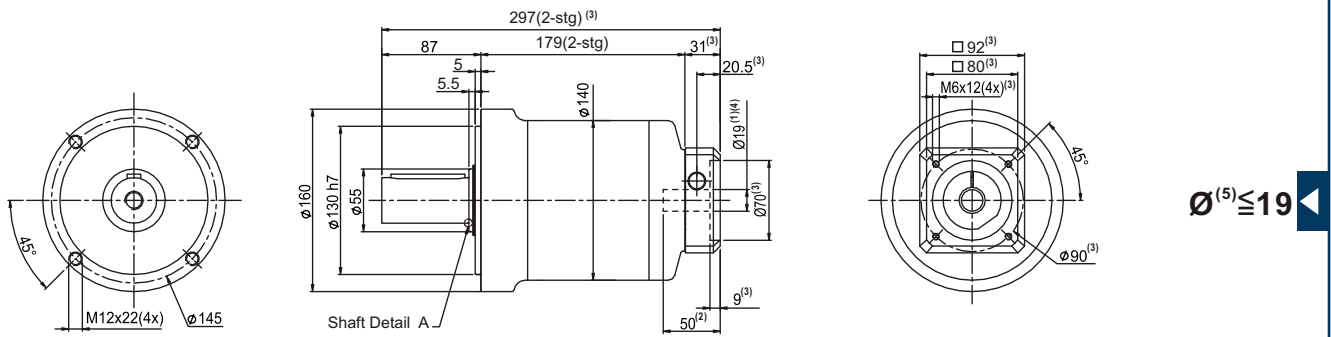
(5) \varnothing = Input shaft diameter.

(6) These values are measured at 3000 rpm without load.

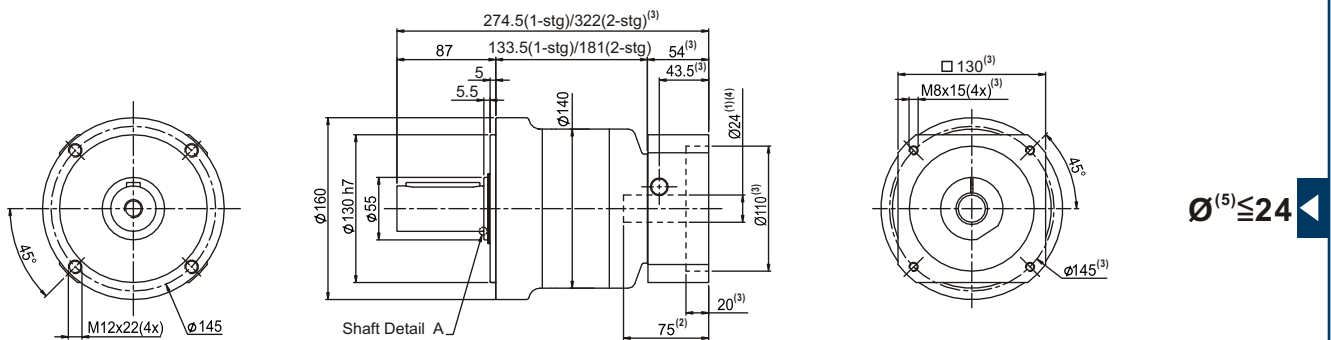
(7) For continuous operation, the service life is 10000 hrs.

(8) These values are measured with ratio=10 (1-stage) and ratio=100 (2-stage) at 3000 rpm.

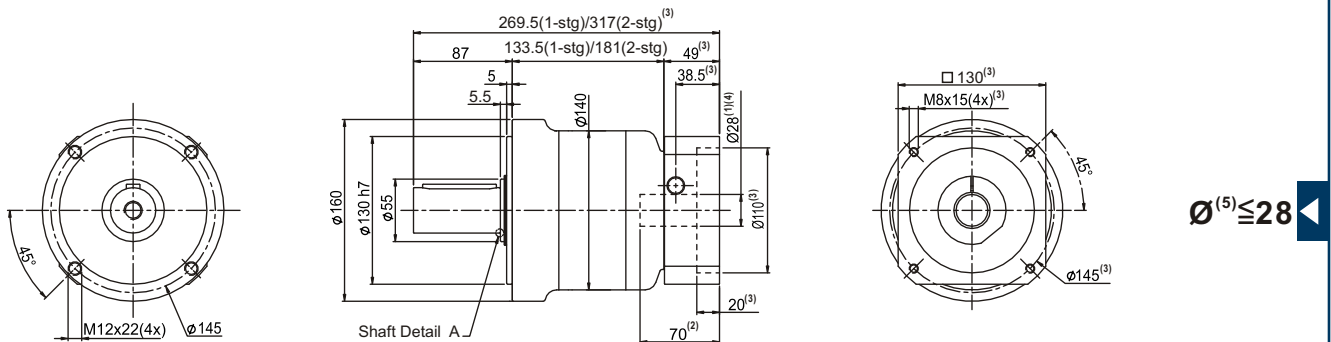
PGII Series Dimension



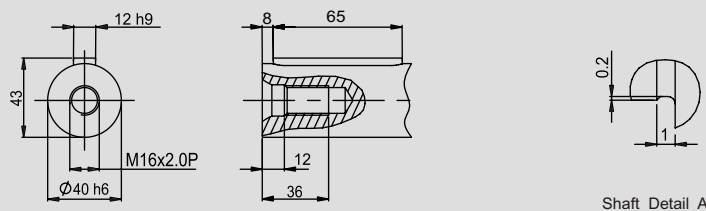
Ø⁽⁵⁾ ≤ 19



Ø⁽⁵⁾ ≤ 24



Ø⁽⁵⁾ ≤ 28

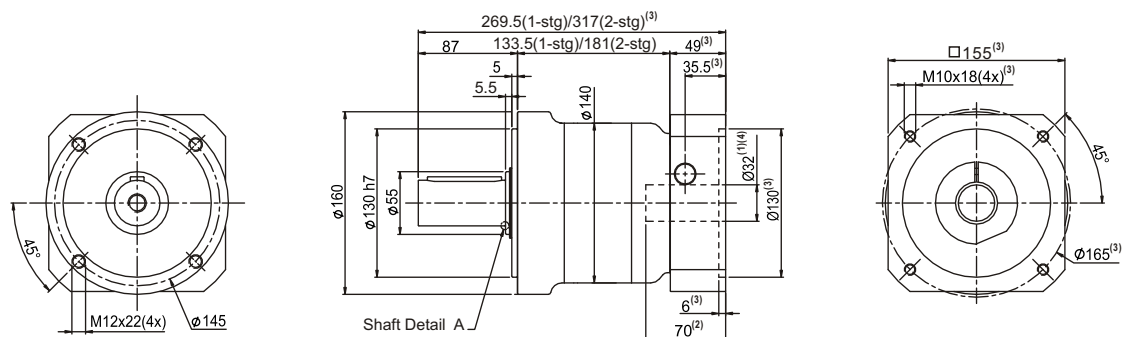


Shaft Detail

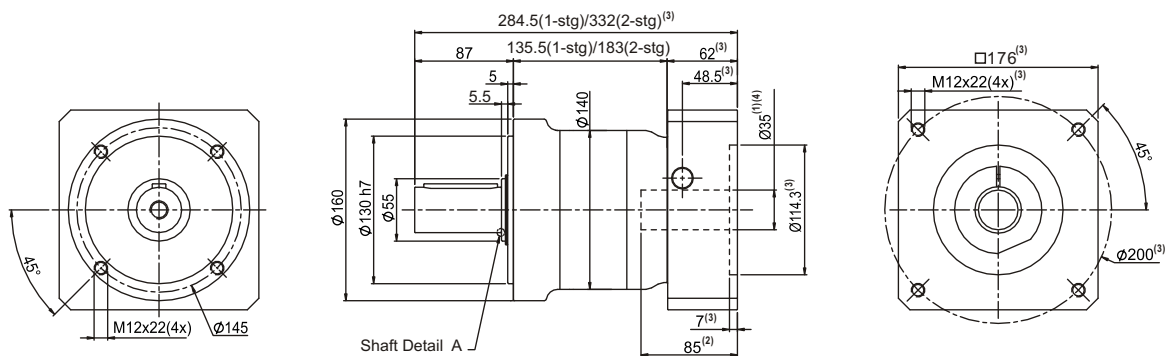
- (1) This dimension refers to motor shaft diameter.
- (2) The maximum motor shaft length. For other Motor specific dimensions, please contact APEX.
- (3) Input dimensions vary according to motor flange.
- (4) Please contact APEX, if there is no proper dimension.
- (5) Ø= Input shaft diameter.

PGII Series Dimension

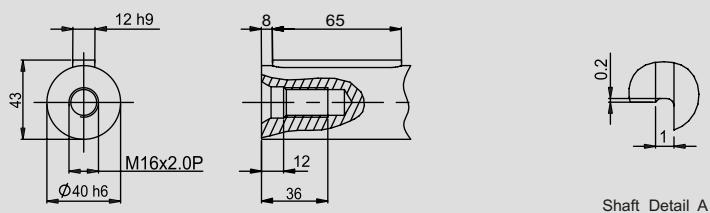
▶ $\varnothing^{(5)} \leq 32$



▶ $\varnothing^{(5)} \leq 35$



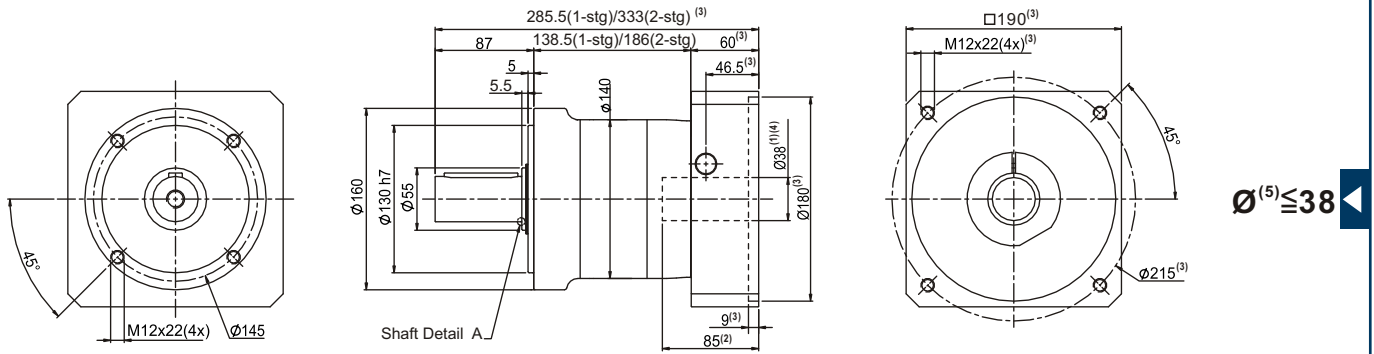
▶ Shaft Detail



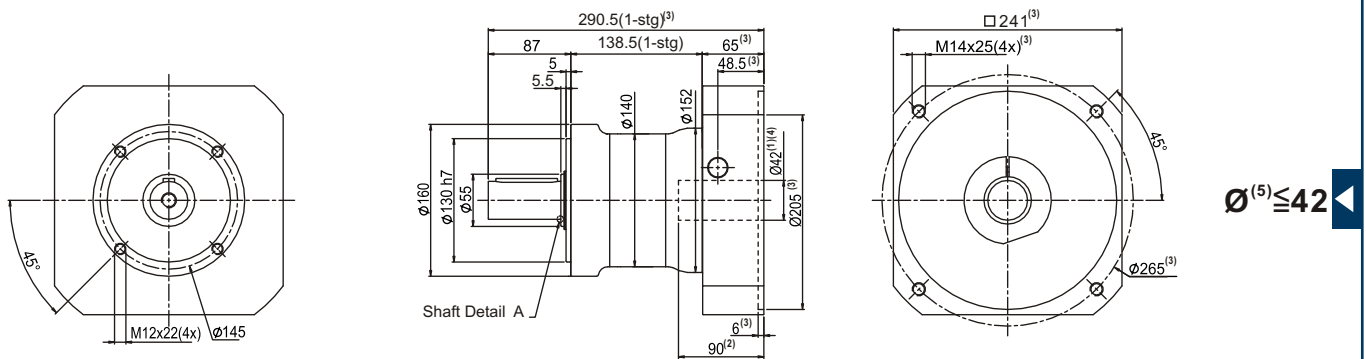
Shaft Detail A

- (1) This dimension refers to motor shaft diameter.
- (2) The maximum motor shaft length. For other Motor specific dimensions, please contact APEX.
- (3) Input dimensions vary according to motor flange.
- (4) Please contact APEX, if there is no proper dimension.
- (5) \varnothing = Input shaft diameter.

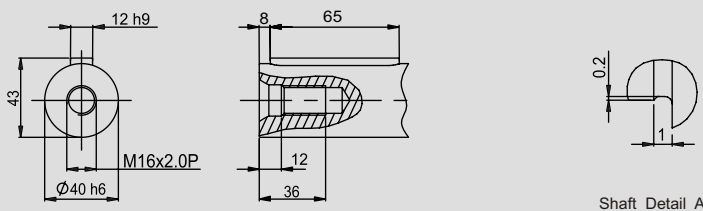
PGII Series Dimension



Ø⁽⁵⁾ ≤ 38



Ø⁽⁵⁾ ≤ 42

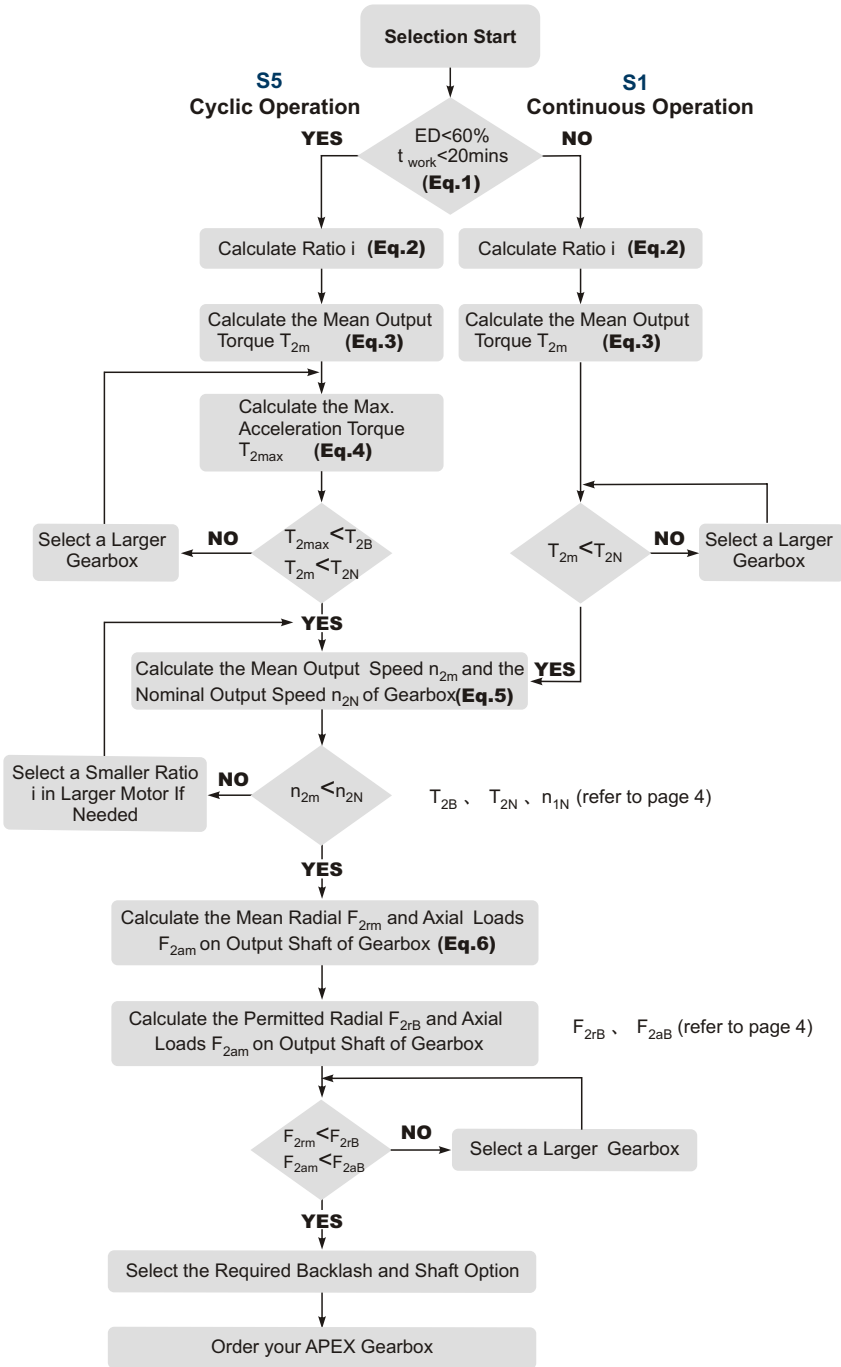


Shaft Detail A

Shaft Detail

- (1) This dimension refers to motor shaft diameter.
- (2) The maximum motor shaft length. For other Motor specific dimensions, please contact APEX.
- (3) Input dimensions vary according to motor flange.
- (4) Please contact APEX, if there is no proper dimension.
- (5) Ø= Input shaft diameter.

Selection of the optimum gearbox



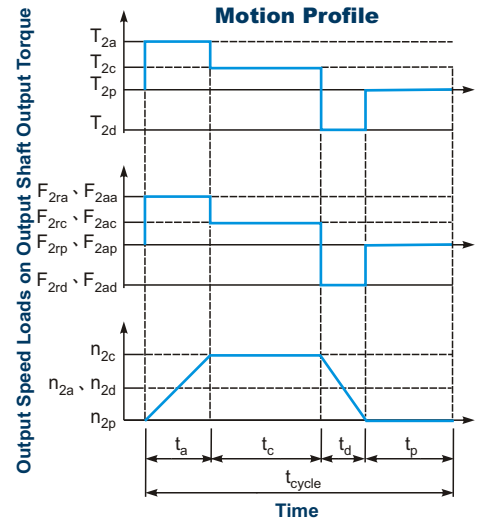
Recommended (for S5 Cycle Operation)

The general design is given for

$$\frac{J_L}{i^2} \leq 4 \times J_m$$

The optimal design is given for

J_L Load Inertia
 J_m Motor Inertia



$$1. ED = \frac{t_a + t_c + t_d}{t_{cycle}} \times 100\%, t_{work} = t_a + t_c + t_d$$

Index : a. Acceleration, c. Constant,
 d. Deceleration, p. Pause **(Eq.1)**

$$2. i \cong \frac{n_m}{n_{work}}$$

n_m Output Speed of the Motor
 n_{work} Working Speed **(Eq.2)**

$$3. T_{2m} = 3 \sqrt{\frac{n_{2a} \times t_a \times T_{2a}^3 + n_{2c} \times t_c \times T_{2c}^3 + n_{2d} \times t_d \times T_{2d}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$

(Eq.3)

$$4. T_{2max} = T_{mB} \times i \times K_s \times \eta$$

where K_s is

| K_s | No. of Cycles / hr |
|-------|--------------------|
| 1.0 | 0 ~ 1,000 |
| 1.1 | 1,000 ~ 1,500 |
| 1.3 | 1,500 ~ 2,000 |
| 1.6 | 2,000 ~ 3,000 |
| 1.8 | 3,000 ~ 5,000 |

T_{mB} Max. Output Torque of the Motor

$$\eta \text{ Efficiency of the Gearbox} \quad \text{b)} \quad \text{(Eq.4)}$$

$$5. n_{2a} = n_{2d} = \frac{1}{2} \times n_{2c}$$

$$n_{2m} = \frac{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}{t_a + t_c + t_d}$$

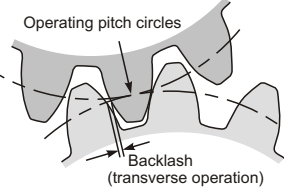
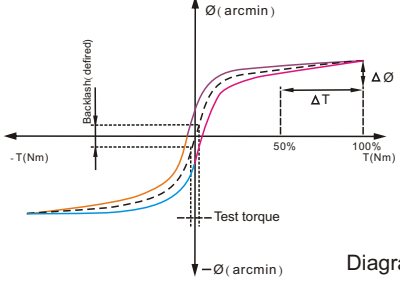
$$n_{2N} = \frac{n_{1N}}{i} \quad \text{b)} \quad \text{(Eq.5)}$$

$$6. F_{2rm} = 3 \sqrt{\frac{n_{2a} \times t_a \times F_{2ra}^3 + n_{2c} \times t_c \times F_{2rc}^3 + n_{2d} \times t_d \times F_{2rd}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$

$$F_{2am} = 3 \sqrt{\frac{n_{2a} \times t_a \times F_{2aa}^3 + n_{2c} \times t_c \times F_{2ac}^3 + n_{2d} \times t_d \times F_{2ad}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$

(Eq.6)

Glossary

| | | |
|-----------------------------------|---------------------|--|
| Emergency Stop Torque T_{2NOT} | Nm | The Emergency Stop Torque is the maximum permitted torque at the output of gearbox. This may happen only occasionally and may not exceed 1000 times during the whole service life. |
| Max. Acceleration Torque T_{2B} | Nm | Under the Cyclic Operation (S5), the Max. Acceleration Torque is the maximum torque which can be transmitted only briefly to the output of gearbox up to 1000 cycles/hr. |
| No Load Running Torque | Nm | The No Load Running Torque is the min. torque to overcome the internal friction of a gearbox without loading*. |
| Nominal Input Speed n_{1N} | rpm | The Nominal Input Speed is the permitted input speed of gearbox by the Continuous Operation (S1) while the housing temperature does not exceed 90°C. This value is measured at environment temperature 25°C. |
| Max. Input Speed n_{1B} | rpm | The Max. Input Speed is the max. permitted input speed of gearbox by the Cyclic operation (S5). This value is measured at environment temperature 25°C and serves as the absolute limit of the gearbox. |
| Backlash | arcmin | <p>The Backlash is the maximum angular measurement between two teeth of gears when the transverse operation occurs (refer to Diagram 1). The arcmin is the measurement unit for the backlash. One arcmin equals 1/ 60 degree, symbolized as 1'.</p>  <p style="text-align: right;">Diagram 1</p> |
| Torsional Rigidity | Nm/arcmin | <p>Torsional Rigidity is the quotient ($\Delta T / \Delta \varnothing$) between the applied torque and resulting torsion angle. This value indicates how many torque needed on gearbox to rotate the output shaft for 1 arcmin. The Torsional Rigidity can be determined by Hysteresis Curve.</p> <p>Hysteresis Curve When the input shaft is locked, increase torque at the output slowly up to T_{2B} in both directions and then release the torque gradually. According to the measured torque and torsion angle, a closed curve will be acquired as Diagram 2.</p>  <p style="text-align: right;">Diagram 2</p> |
| Efficiency η | % | The transmission efficiency of the gears inside a gearbox (without friction). |
| Operating Temperature | ° C | The Operating Temperature indicates the temperature of gearbox housing. |
| Lubrication | | APEX uses synthetic lubrication grease. There are other grease available, please contact APEX. |
| Running Noise | dB(A) | The Running Noise is measured depends on gearbox size, the ratio and the speed*. Higher speed induces usually higher noise level, while higher ratio induces lower noise level. |
| Moment of Inertia J_1 | kg. cm ² | The Moment of Inertia J1 is a measurement of the effort applied to an object to maintain its momentary condition at rest or rotating. |
| Breakaway Torque | Nm | The Breakaway Torque is the minimum torque to start the rotation from the input side of gearbox. A smaller size or a higher ratio gearbox requests less Breakaway Torque. |
| Back Driving Torque | Nm | The Back Driving Torque is the minimum torque to start the rotation from the output side of gearbox. A larger size or a higher ratio gearbox requests greater Back Driving Torque. |

* This value is measured at environment temperature 25°C and the input speed 3000 rpm. If the Nominal Input Speed n_{1N} of gearbox is over 3000 rpm, this value is measured by that specific Nominal Input Speed.

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APEX-2013-04-PII SERIES-1.0E-2.0V

